DATA SHEET

TMI-Orion Dynamics

Electrical Linear Actuator



Underwater Electrical Linear Actuator module

The Electrical Linear Actuator (ELA) is a high-performance, compact and reliable module designed for underwater operation down to a depth of 500 meters. The Electrical Linear Actuator module offers intuitive programmable position controls and embedded controllers. This modular system is also equipped with a connector for an additional module (optional cameras, projectors...). It is adapted to numerous operations and can be mounted on TMI-Orion ROV platforms and retrofitted to most of ROV systems.

- Manipulators component
- Underwater motion system (camera, projector pan and tilt, sonar, thruster...)
- Ballast correction system
- Sampling system
- ROV locking system
- Subaquatic tooling / ROV equipment
- For scientific community Environment Energy -Aquaculture...

SPECIAL FEATURES

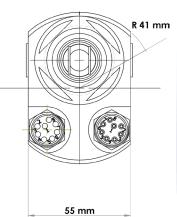
- Ideal for applications with large thrusts where precision and motion control are needed.
- Position feedback

- 1 connector available for add-on capacity (additional actuators, camera, projector...)
- With embedded electronic controller (no external POD required)

TECHNICAL SPECIFICATIONS

Material	Hard anodized aluminum (body), Stainless steel (rod)
Depth rating	500 m
Dimensions	D. 82 mm x I. 256 mm
Range	up to 85 mm
Weight	2 kg in air 1.2 kg in fresh water
Operating temperature	From -10°C to +60°C
Storage temperature	From -20°C to +60°C
Connector	In: SubConn / out: SubConn MCBH8F (chainable with other TMI-Orion products)
Power supply	9-24 VDC. The characteristics are done with 24 VDC nominal (40 W max.)
Control bus	RS485 (115 200 bauds)
Thrust capability	200 kg (max)
Rod speed	Up to 4 mm per second (configurable)





174 mm

Range 85 mm

255.5 mm min

Electrical Linear Actuator Side view

Electrical Linear Actuator Front view



SOFTWARE AND RELATED PRODUCTS

Monitoring software

The Electrical Linear Actuator Module comes with a monitoring software.

Other products

The Electrical Linear Actuator Module can equip the S-ROV or the Electrical Manipulator Arm. Please visit our website for more information.

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